Calculations in Deformation Theory

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Deformation Basics

Computing Versal Deformations



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Basic idea: we deform X by perturbing the f_i .

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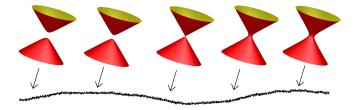
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- The fiber over 0 is just X. The fiber over $t \neq 0$ is smooth.



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Problem: the relation $f_2 - f_1 = f_3$ doesn't lift to a relation among the \tilde{f}_i .

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Consider the start of a free resolution of S/I:

$$\cdots \longrightarrow S^n \xrightarrow{R} S^m \xrightarrow{F} S \longrightarrow S/I \longrightarrow 0.$$

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Definition

The relations R lift with respect to \widetilde{F} subject to equations $g_1, \ldots, g_k \in T$ if there exists a $\widetilde{R} : \widetilde{S}^n \to \widetilde{S}^m$ restricting to R such that

$$\operatorname{Im}\left(\widetilde{F}\cdot\widetilde{R}\right)\subset\left\langle g_{i}\right\rangle$$

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A relation matrix is given by

$$R = \begin{pmatrix} x_4 & x_3 \\ x_2 & x_1 \\ -x_3 & -x_2 \end{pmatrix}.$$

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$$\widetilde{F} = \left(\begin{array}{cc} x_1 x_3 - x_2^2 + t x_2 & x_2 x_4 - x_3^2 - t x_4 & x_1 x_4 - x_2 x_3 \end{array}\right).$$

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- A lifting of R is given by \widetilde{R} .

Definition

A deformation of $X \subset \mathbb{C}^d$ over $Z = \text{Spec}(T/\langle g_i \rangle)$ consists of a perturbation \widetilde{F} of F such that the relations lift with respect to \widetilde{F} , subject to the equations g_i .

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- \widetilde{F} defines a scheme $\mathcal{X} \subset \mathbb{C}^d \times Z$ and a map $\pi : \mathcal{X} \to Z$.
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Example

For hypersurfaces, arbitrary perturbations are allowed.

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- Consider the deformation given by $\tilde{f} = x^2 + y^2 z^2 t$.
- Can we induce the deformation given by $x^2 + y^2 z^2 sz$?

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- Consider the deformation given by $\tilde{f} = x^2 + y^2 z^2 t$.
- Can we induce the deformation given by $x^2 + y^2 z^2 sz$?
- ► Yes! Substitute $t = -\frac{1}{4}s^2$ and take the change of coordinates $z \mapsto (z + \frac{1}{2}s)$.

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Q: How can we compute a versal deformation of X?A: Using Macaulay2 and the package VersalDeformations.

Deformation Basics

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• A formally versal deformation of X (more details later). Basic approach: iteratively lift deformations in T_X^1 to larger and larger base spaces.

Computational Example I: Our A₁ Singularity

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Any first order deformation can be induced from $F + t_1 \cdot 1 = (x^2 + y^2 - z^2 + t_1)$ with $t_1^2 = 0$.

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- ► *GL* is a list of matrices whose sum *G* contains the equations cutting out the versal base space.

These matrices solve the "deformation equation"

$$(\widetilde{F}\cdot\widetilde{R})^{\mathrm{tr}}+C\cdot G=0$$

where C is the sum of the list CL.

Take

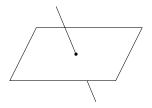
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Take F to be the transpose of
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► The base space has two components, C³ and C meeting in a point.



Total Spaces Over the Components

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- Can calculate versal deformations for projective X.
- Can calculate local (multigraded) Hilbert schemes.
- Can lift deformations in given tangent direction to a one-parameter family.

A Toric Fano Threefold

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Let X be the projective subscheme of \mathbb{P}^8 cut out by

$$\begin{array}{ll} x_{i+1}x_{i-1} - x_iy_0 & 1 \le i \le 6 \\ x_ix_{i+3} - y_0^2 & 1 \le i \le 3 \\ y_1y_2 - y_0^2 \end{array}$$

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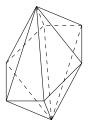
where \mathbb{P}^8 has coordinates $x_1, \ldots, x_6, y_0, y_1, y_2$.

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Similar calculations + lots of hard work can be used to classify all smoothings of Gorenstein Fano toric threefolds of degree ≤ 12 .

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 T_X^1 may be computed as the cokernel of

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where J is the Jacobian matrix $\left(\frac{\partial f_i}{\partial x_j}\right)_{ij}$.

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where J is the Jacobian matrix $\left(\frac{\partial f_i}{\partial x_j}\right)_{ij}$. If dim Sing(X) = 0, then dim_C $T_X^1 < \infty$.

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• Choose $\phi_i \in \text{Hom}(S^m, S)$ $i = 1, \dots, e$ which represent a basis of T_X^1 .

Choose φ_i ∈ Hom(S^m, S) i = 1,..., e which represent a basis of T¹_X.

• Set $T = \mathbb{C}[t_1, \ldots, t_e]$ with maximal ideal $\mathfrak{m} = \langle t_1, \ldots, t_e \rangle$.

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▶ The relations *R* lift with respect to F^1 subject to \mathfrak{m}^2 to some $R^1: \widetilde{S}^n \to \widetilde{S}^m$.

- Choose φ_i ∈ Hom(S^m, S) i = 1,..., e which represent a basis of T¹_X.
- Set $T = \mathbb{C}[t_1, \ldots, t_e]$ with maximal ideal $\mathfrak{m} = \langle t_1, \ldots, t_e \rangle$.
- Let $F^1 \colon \widetilde{S}^m \to \widetilde{S}$ be the perturbation of $F = F^0$ defined by

$$F^1 = F^0 + \sum_{i=1}^e t_i \phi_i.$$

▶ The relations *R* lift with respect to F^1 subject to \mathfrak{m}^2 to some $R^1: \widetilde{S}^n \to \widetilde{S}^m$. This can be computed using matrix quotients in Macaulay2.

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- 1. $F^i \equiv F^{i-1} \mod \mathfrak{m}^i$, $R^i \equiv R^{i-1} \mod \mathfrak{m}^i$;
- 2. $F^i \cdot R^i \equiv 0 \mod \mathfrak{m}^{i+1}$.

Goal: lift this deformation to a "larger" base space.
Given Fⁱ⁻¹ ∈ Hom(S̃^m, S̃), Rⁱ⁻¹ ∈ Hom(S̃ⁿ, S̃^m), we would like to find Fⁱ and Rⁱ such that

Fⁱ ≡ Fⁱ⁻¹ mod mⁱ, Rⁱ ≡ Rⁱ⁻¹ mod mⁱ;
Fⁱ ⋅ Rⁱ ≡ 0 mod mⁱ⁺¹.

In general, this is not possible!!!

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- ▶ It is possible to inductively construct F^i , R^i , $G^{i-2} \in \text{Hom}(\widetilde{S}, \widetilde{S}^i)$, $C^{i-2} \in \text{Hom}(\widetilde{S}^i, \widetilde{S}^n)$ solving

$$(F^i R^i)^{\mathrm{tr}} + C^{i-2} G^{i-2} \equiv 0 \mod \mathfrak{m}^{i+1}.$$

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- 1. $F^i, R^i, G^{i-2}, C^{i-2}$ reduce to $F^{i-1}, R^{i-1}, G^{i-3}, C^{i-3}$ modulo \mathfrak{m}^i ;
- 2. G^{i-2} and C^{i-2} vanish for i < 2;
- 3. C^0 is of the form $V \cdot D$, where $D \in \text{Hom}(S^d, S^d)$ is a diagonal matrix.

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The perturbation $\lim_{i\to\infty} F^i$ gives a formally versal deformation over the base space cut out by the rows of $\lim_{i\to\infty} G^{i-2}$.