

Math 221 Final Project: A Tighter Forward Error Estimate

Vasily Volkov and Sage Briscoe

December 7, 2007

The Problem

Our goal is to substitute LAPACK's estimate of forward error $|A^{-1}| \cdot |r| + O(\epsilon)$ with a hopefully tighter estimate $|A^{-1}r| + O(\epsilon)$.

We present a numerically robust expression for the $O(\epsilon)$ term and experimentally validate the new method.

Given A , b and $\hat{x}$, a proposed solution to $Ax = b$, we estimate the forward error $\Delta x = \hat{x} - x$:

$$|\Delta x| = |\hat{x} - x| = |A^{-1}r| \leq |A^{-1}| \cdot |r|,$$

where $r = A\hat{x} - b$. We can compute $|||A^{-1}| \cdot |r|||_{\infty}$ by Hager's estimator. If we take into account that the floating point residual $\hat{r} = \text{fl}(A\hat{x} - b)$ differs from r by as much as $\Delta r = r - \hat{r}$, $|\Delta r| \leq \epsilon(n+1)(|A| \cdot |\hat{x}| + |b|)$, where ϵ is the machine precision, then

$$\begin{aligned} |A^{-1}r| &\leq |A^{-1}| \cdot |r| \\ &= |A^{-1}| \cdot |\hat{r} + \Delta r| \\ &\leq |A^{-1}| \cdot (|\hat{r}| + |\Delta r|) \\ &\leq |A^{-1}| \cdot (|\hat{r}| + \epsilon(n+1)(|A| \cdot |\hat{x}| + |b|)). \end{aligned}$$

Our Proposed Error Estimate

Given A , b and $\hat{x}$ as before, as well as L and U corresponding to an LU decomposition of A , we will attempt to create a tighter bound on the forward error. If $r = \hat{r} + \Delta r$, then

$$|A^{-1}r| = |A^{-1}(\hat{r} + \Delta r)| \leq |A^{-1}\hat{r}| + |A^{-1}| \cdot |\Delta r|.$$

The term $|A^{-1}| \cdot |\Delta r|$ does not differ from as in the LAPACK's bound, so we need to bound $|A^{-1}\hat{r}|$.

Let ΔA be the backward error of LU-factorization, i.e.

$LU = A + \Delta A$, and let $\hat{f} = \text{fl}(A^{-1}\hat{r}) = (A + \widehat{\Delta A})^{-1}\hat{r}$ where $A + \widehat{\Delta A} = (L + \Delta L)(U + \Delta U)$. Then $\hat{f} = (U + \Delta U)^{-1}(L + \Delta L)^{-1}\hat{r}$ is readily found using triangular solves.

Then, since $\hat{r} = (L + \Delta L)(U + \Delta U)\hat{f}$, we see

$$\begin{aligned}A^{-1}\hat{r} &= A^{-1}(L + \Delta L)(U + \Delta U)\hat{f} \\&= A^{-1}(LU + \Delta LU + L\Delta U + \Delta L\Delta U)\hat{f} \\&= A^{-1}(A + \Delta A + \Delta LU + L\Delta U + \Delta L\Delta U)\hat{f} \\&= \hat{f} + A^{-1}(\Delta A + \Delta LU + L\Delta U + \Delta L\Delta U)\hat{f}\end{aligned}$$

and

$$\begin{aligned}|A^{-1}\hat{r}| &\leq |\hat{f}| + |A^{-1}| \cdot (|\Delta A| + |\Delta LU| + |L\Delta U| + |\Delta L\Delta U|)|\hat{f}| \\&\leq |\hat{f}| + |A^{-1}| \cdot (|LU - A| + 3\epsilon(n+1)|L| \cdot |U|)|\hat{f}|.\end{aligned}$$

Putting it together we get

$$\begin{aligned}
 |A^{-1}r| &\leq |A^{-1}\widehat{r}| + |A^{-1}| \cdot |\Delta r| \\
 &\leq |\widehat{f}| + |A^{-1}| \cdot (|LU - A| + 3\epsilon(n+1)|L| \cdot |U|)|\widehat{f}| + \\
 &\quad |A^{-1}| \cdot \epsilon(n+1)(|A| \cdot |\widehat{x}| + |b|) \\
 &= |\widehat{f}| + |A^{-1}| \cdot \\
 &\quad (|LU - A| \cdot |\widehat{f}| + \epsilon(n+1)(3|L| \cdot |U| \cdot |\widehat{f}| + |A| \cdot |\widehat{x}| + |b|))
 \end{aligned}$$

and then

$$||A^{-1}r||_{\infty} \leq ||\widehat{f}||_{\infty} + |||A^{-1}| \cdot |\xi|||_{\infty}$$

for $\xi = |LU - A| \cdot |\widehat{f}| + \epsilon(n+1)(3|L| \cdot |U| \cdot |\widehat{f}| + |A| \cdot |\widehat{x}| + |b|)$.

Where we do Better

Our estimate for the forward error differs from the LAPACK error bound only in the way we bound $|A^{-1}\hat{r}|$, so to find an example where our bound performs better than the LAPACK bound we need to find an A and r such that $\|A^{-1}r\| \ll \|A^{-1}\| \cdot \|r\|$.

Thus we seek examples where A is ill-conditioned. If r is in the direction of the largest singular value of A , σ_1 , and $|r|$ is in the direction of a smaller singular value then our bound will be tighter.

Experimental Results

$$n = 10$$

matrix A has singular values $1, \alpha, \alpha^2, \dots$ for $\alpha < 1$

$$\kappa(A) = 1/\alpha^{n-1}$$

measure how much our bound is tighter than LAPACK's bound
take maximum over 100 tests.

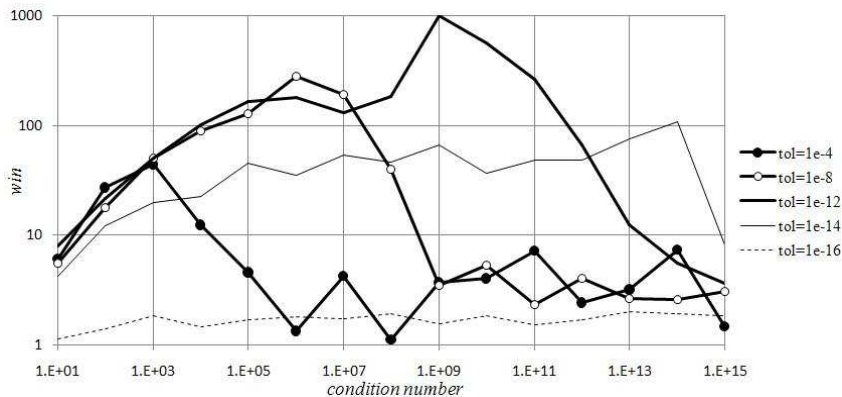
compute $|A^{-1}| \cdot |w|$ is using explicit matrix inversion, to avoid
underestimation in Hager's estimator.

Experimental Results

Solve $Ax = b$ using a perturbed LU-factorization, b is random

tol: size of perturbation

win: LAPACK's bound divided by our bound



Experimental Results

$$\text{SVD: } A = U\Sigma V^T$$

"largest": $b = v_1$

"top": $b = c^T(v_1, \dots, v_{n/2})$, c is a random vector

