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## Math221: Matrix Computations

## Homework #2 Solutions

• 2.3: We need relevant vectors in equation (2.1) to have the same direction in order for (2.3) to be an equation. Hence we let

$$A^{-1}\delta b = \alpha \delta x, \quad A^{-1}\delta A \hat{x} = -\beta \delta x,$$

where  $\alpha$  and  $\beta$  are scalars to be determined. This leads to

$$\delta b = \alpha A \delta x$$
 and  $\delta A \hat{x} = -\beta A \delta x$ .

With the trick in the proof of Theorem 2.1, we conclude that the minimum 2-norm solution for  $\delta A$  from the above equation is

$$\delta A = -\frac{\beta A \delta x \hat{x}^T}{\hat{x}^T \hat{x}}.$$
(1)

With these choices, the right hand side of inequality (2.3) becomes  $(|\alpha| + |\beta|) ||A^{-1}||_2 ||A\delta x||_2$ , whereas the right hand side of (2.1) becomes  $(\alpha + \beta) \delta x$ . It is obvious that for (2.3) to be an equation, we must first set  $\alpha \ge 0$ ,  $\beta \ge 0$  and  $\alpha + \beta = 1$ . With these conditions, the equation

$$(A + \delta A)\,\hat{x} = b + \delta b \tag{2}$$

holds for any  $\hat{x} = x + \delta x$  as long as  $\hat{x} \neq 0$ . Hence we can choose  $\hat{x}$  in anyway we wish, as long as  $\|\delta x\|_2$  is sufficiently small.

With the choice of  $\alpha$  and  $\beta$ , the right hand side of inequality (2.3) has become  $||A^{-1}||_2 ||A\delta x||_2$ . Let

$$A\delta x = \gamma u$$
, or  $\delta x = \gamma A^{-1}u$ ,

where  $\gamma \geq 0$  is a scalar to be determined, and u is a unit vector such that  $||A^{-1}||_2 = ||A^{-1}u||_2$ . For any  $\delta x$  in the above form, equation (2) is satisfied and (2.2) becomes an exact equation. In the following, we have to further specify  $\gamma$ , with given values of  $||\delta A||_2$  and  $||\delta b||_2$ , which are assumed to be sufficiently small. In fact, with our choice of  $\delta x$ , we have

$$\delta b = \alpha \gamma u$$
 and  $\delta A = -\frac{\beta \gamma u \hat{x}^T}{\hat{x}^T \hat{x}}$ 

Taking norms on both equations, we have

$$\alpha \gamma = \|\delta b\|_2$$
 and  $\beta \gamma = \|\delta A\|_2 \|\hat{x}\|_2$ .

Together with  $\alpha + \beta = 1$ , we have

$$\alpha = \frac{\|\delta b\|_2}{\gamma}, \quad \beta = \frac{\|\delta A\|_2 \|\hat{x}\|_2}{\gamma},$$

where

$$\gamma = \|\delta b\|_2 + \|\delta A\|_2 \|\hat{x}\|_2 = \|\delta b\|_2 + \|\delta A\|_2 \|x + \gamma A^{-1}u\|_2, \tag{3}$$

which is a non-linear equation in  $\gamma$ . For the above choices to make sense, we now must show that this equation does have a solution.

One way to show that this equation has indeed a solution is to use fixed-point iteration. Define  $\gamma_0 = \|\delta b\|_2 + \|\delta A\|_2 \|x\|_2$  and

$$\gamma_{k+1} = \|\delta b\|_2 + \|\delta A\|_2 \|x + \gamma_k A^{-1} u\|_2, \quad k = 0, 1, 2, \cdots.$$

One can show that for all k > 1,

$$0 \le \gamma_k \le \frac{\|\delta b\|_2 + \|\delta A\|_2 \|x\|_2}{1 - \|\delta A\|_2 \|A^{-1}\|_2},$$
  
$$|\gamma_{k+1} - \gamma_k| \le |\gamma_k - \gamma_{k-1}| \|\delta A\|_2 \|A^{-1}\|_2.$$

Hence the  $\gamma$  sequence must be convergent provided that  $\|\delta A\|_2 \|A^{-1}\|_2 < 1$ , which is true since  $\|\delta A\|_2$  is assumed to be sufficiently small. The limit of this sequence is the solution of the above non-linear equation.