

Math128B
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 Background Material on Norms

1. $\|x\|_p$ denotes the p-norm of a vector in \mathbb{R}^n . If no p is indicated, then $p = 2$ is assumed.
2. We define the ‘operator p-norm’ of A as

$$\|A\|_p \stackrel{\text{def}}{=} \sup_{x \neq 0} \frac{\|Ax\|_p}{\|x\|_p} = \sup_{\|x\|_p=1} \|Ax\|_p$$

3. (Medium)

$$\langle y, x \rangle \stackrel{\text{def}}{=} y'x = \|x\| \|y\| \cos \angle(x, y)$$

An easy consequence of this is the ‘Cauchy-Schwarz-Bunyakovsky Inequality’ (with equality iff x and y parallel):

$$|\langle y, x \rangle| \leq \|x\| \|y\|$$

4. (Medium) If $l : \mathbb{R}^n \rightarrow \mathbb{R}^1$ is linear then there is a unique $y \in \mathbb{R}^n$ such that $l(x) = \langle y, x \rangle \forall x \in \mathbb{R}^n$. Since the $y \in \mathbb{R}^n$ depends on l , we write $y = y_l$. One should think of y_l as a row vector which operates on $x \in \mathbb{R}^n$ by dot-ing x with y_l :

$$l(x) = [\dots y_l \dots] \begin{bmatrix} \vdots \\ x \\ \vdots \end{bmatrix} \quad (\text{clearly linear in } x)$$

5. (Easy) By (1), it makes sense to ask about the ‘operator norm’ of the linear operator $l : \mathbb{R}^n \rightarrow \mathbb{R}^1$. By (3) this turns out to be equal to $\|y_l\|$ where y_l is determined by (4).

6. (Hard) The operator norm defined in (2) can also be given by the following when $p = 2$:

$$\|A\| = \sup_{\|x\|=\|y\|=1} \langle Ax, y \rangle$$

7. (Easy) Using (5) and (6) we can prove $\|A^*\| = \|A\|$
8. (Easy) $\|AB\| \leq \|A\| \|B\|$. For general A and B equality is *not* achieved, (e.g. $A = B = \begin{pmatrix} 0 & 1 \\ 0 & 0 \end{pmatrix}$)
9. (Easy) Using (7) and (8) we can prove $\|A^*A\| \leq \|A\|^2$
10. (Hard) Using (3) and (6) we can prove $\|A^*A\| \geq \|A\|^2$.
11. (Easy) (9) and (10) imply $\|A^*A\| = \|A\|^2$

12. (Easy) Using 11 we can prove if A is Hermitian, then $\|A^2\| = \|A\|^2$ (note that $A = \begin{pmatrix} 0 & 1 \\ 0 & 0 \end{pmatrix}$ example in (8) is not Hermitian).
13. For any $A : \mathbb{R}^n \rightarrow \mathbb{R}^n$ we define the spectrum of A :
- $$\sigma(A) \stackrel{\text{def}}{=} \{ \lambda \in \mathbb{C} \mid \lambda \text{ is an eigenvalue of } A, \text{ i.e. is a root of } A's \text{ characteristic polynomial} \}$$
14. For any $A : \mathbb{R}^n \rightarrow \mathbb{R}^n$ we define the spectral radius of A :
- $$\rho(A) \stackrel{\text{def}}{=} \text{the maximum (complex) norm of the eigenvalues of } A = \text{"size" of } \sigma(A)$$
15. (Easy) $\sigma(A^*) = \overline{\sigma(A)}$ and $\rho(A^*) = \rho(A)$ and $\rho(A^n) = \rho(A)^n$
16. (Easy) $\rho(A) \leq \|A\|$ ($\begin{pmatrix} 0 & 1 \\ 0 & 0 \end{pmatrix}$ is example of strict inequality)
17. (Homework) If A is Hermitian, then $\rho(A) = \|A\|$
18. (Easy) (17) implies $\rho(A^*A) = \|A^*A\|$
19. (Easy) (18) and (11) imply $\rho(A^*A) = \|A\|^2$, i.e. $\|A\| = \sqrt{\rho(A^*A)}$ = formula for $\|A\|_2$

Some more definitions:

| DEFINING PROPERTY | NAME | SPECTRUM | INTERPRETATION |
|----------------------------|------------|---|--|
| $A^t A = A A^t = I$ real | orthogonal | $\sigma(A) \subset \{z \in \mathbb{C} \mid z = 1\}$ | preserves Euclidean length |
| $A^* A = A A^* = I$ | unitary | $\sigma(A) \subset \{z \in \mathbb{C} \mid z = 1\}$ | complex version |
| $A^t = A$ real | symmetric | $\sigma(A) \subset \mathbb{R}$ | stretch in perpendicular directions |
| $A^* = A$ | Hermitian | $\sigma(A) \subset \mathbb{R}$ | complex version |
| $A = B^* B$ | positive | $\sigma(A) \subset \mathbb{R}^{\geq 0}$ | symmetric, positive stretches |
| $A^{-1} = A$ ($A^2 = I$) | involution | $\sigma(A) \subset \{-1, 1\}$ | oblique reflection |
| $A^{-1} = A = A^*$ | reflection | $\sigma(A) \subset \{-1, 1\}$ | perpendicular reflection |
| $A^2 = A$ | idempotent | $\sigma(A) \subset \{0, 1\}$ | oblique projection |
| $A^2 = A = A^*$ | projection | $\sigma(A) \subset \{0, 1\}$ | orthogonal projection |
| $A^* A = A A^*$ | normal | $\sigma(A)$ | iff diagonalizable (via unitary change of basis) |

Additional facts:

1. Diagonalizable matrices share eigenspaces iff they commute iff simultaneously diagonalizable
2. Every real matrix is sum of symmetric and skew-symmetric ($A^t = -A$)
3. Every complex matrix is sum of Hermitian and skew-Hermitian ($A^* = -A$)
4. A matrix is (unitarily) diagonalizable iff its Hermitian and skew-Hermitian parts commute